Numerical study for the estimation of the hydrodynamic coefficients of current drag in port assistance maneuvers (dock) for the Colombian Navy frigates by means of CFD

Estudio numérico para la estimación de los coeficientes hidrodinámicos de arrastre de corriente en maniobras de asistencia en puerto (muelle), para fragatas de la Armada Colombiana mediante CFD

Abstract

Computational Fluid dynamics (CFD) has become nowadays an important tool in the process of hydrodynamic design of modern ships. CFD is used to model any phenomena related to fluid flow in a control volume like a ship or any offshore structure in the sea. In the present study, the Current force drag coefficients for a Colombian Navy Frigate in deep and shallow water are estimated through application of CFD, which are required to estimate the bollard pull for assisting maneuvers at port. The study shows the process of simulating the ship current drag coefficients using the CFD simulations method which is conducted using STAR-CCM+ software package. The Almirante Padilla class Frigate ship CFD scale model is researched. The results show the ship current drag coefficient calculated considering a current speed of 1 knot with a 90° drift angle for the full-scale ship. The model configuration of the present simulation is based on the procedure recommended and published in the Lloyds Register OCIMF and the UFC mooring report for the estimation of the current drag coefficient.

Key words: CFD, Current draft coefficient, STAR-CCM+, OCIMF, ITTC, Bollard pull.

Resumen

La dinámica de fluidos computacional (CFD) se ha convertido hoy en día en una herramienta importante en el proceso de diseño hidrodinámico de los buques modernos. El CFD se utiliza para modelar cualquier fenómeno relacionado con el flujo de fluidos en un volumen de control como un buque o cualquier estructura offshore en el mar. En el presente estudio se estiman los coeficientes de arrastre generados por la fuerza inducida por la corriente para una Fragata de la Armada Colombiana en aguas profundas y poco profundas mediante la aplicación de CFD, para estimar la potencia de tiro requerida en las maniobras de asistencia en muelle. El estudio muestra el proceso de simulación de los coeficientes de arrastre de la corriente del buque mediante el método de simulaciones CFD que se realiza mediante el paquete de software STAR-CCM+. Se investiga el modelo a escala de CFD del buque Fragata clase Almirante Padilla. Los resultados muestran el coeficiente de arrastre de la corriente del buque calculado, considerando una velocidad de la corriente de 1 nudo con un ángulo de incidencia de 90° para el buque a escala real. La configuración del modelo de la presente simulación se basa en el procedimiento recomendado y publicado por Lloyds Register OCIMF y en el manual UFC para la estimación del coeficiente de arrastre de corriente.

Palabras claves: CFD, Coeficiente de arrastre de corriente, STAR-CCM+, OCIMF, ITTC, Fuerza de tiro.

DOI: https://doi.org/10.25043/19098642.233

Mauricio García¹
Luis Daniel Leal²
Bharat Verma³
Nicolás Ruíz⁴

¹ COTECMAR. Cartagena, Colombia. Email: mgarcian@cotecmar.com
² COTECMAR. Cartagena, Colombia. Email: lleal@cotecmar.com
³ COTECMAR. Cartagena, Colombia. Email: bharat@cotecmar.com
⁴ COTECMAR. Cartagena, Colombia. Email: nruiz@cotecmar.com
Introduction

The bollard pull capacity corresponds to the available pulling power capacity of a vessel given by its propulsion system. It is the thrust force supplied by the propulsion through a towline to a fixed point located on land when the towline is tensioned and the vessel’s ground speed is equal to zero. This value corresponds to one of the most important parameters required to perform berthing/rigging operations and corresponds to the maximum pulling force that a tug will need to ensure safe maneuvering in port. This parameter varies depending on the local weather conditions at the port of arrival or departure, as well as on the hull shape and the respective loading condition of the vessel.

The required drag or draft force is a combination of three main components: the hydrodynamic, aerodynamic and inertial forces that occur during the maneuver. In addition, the hydrodynamic forces can be divided into two main components: a) the forces generated by the waves, and b) the force generated by the current velocity that exists at the location of the vessel’s maneuver. Other factors, such as dock construction, under keel clearance and backing thrusters, are also important in estimating the required final draft force.

Simplified formulations are available in the literature to help obtain the magnitudes of these forces. [1]. The most common forms of these equations are described below:

Wind-induced forces

The wind induced forces follow the general form of the drag coefficient defined for fluids. The general form of the equation for the cross-sectional wind force exerted for a vessel is obtained from the guidelines given by the UFC [2] as shown:

\[ F_{yw} = 0.5 \rho_w V_w^2 A_w C_{yw} f_{yw}(\theta_w) \]  

(1)

Where, \( F_{yw} \) is the transverse force of the wind, \( \rho_w \) is the air density, \( V_w \) corresponds to the wind speed, \( A_w \) is the longitudinal projected area of the vessel, \( C_{yw} \) is the transverse drag coefficient and \( f_{yw}(\theta_w) \) is defined as the shape function that takes into account the angle of incidence of the wind.

Current induced forces

The current-induced forces also follow the general form of the drag coefficient equation. The CFU document describes it as:

\[ F_{yc} = 0.5 \rho_w V_c^2 L_{WL} T C_{yc} \sin(\theta_c) \]  

(2)

Where, \( F_{yc} \) is the transverse force induced by the current, \( \rho_w \) is the density of the water, \( V_c \) is the velocity of the current, \( L_{WL} \) is the length of the water line, \( T \) is the draft, \( C_{yc} \) is the transverse drag coefficient, and \( \theta_c \) is the angle of the current direction with respect to the vessel. [2]. The Fig. 1 shows the longitudinal view corresponding to the draft used, and is applied to estimate the projected areas required in the analytical formulation.

Wave-induced forces

Considering a zero towing speed, the wave-induced force can be estimated using the formula found in the DNV guidelines [3] guidelines, as indicated:

\[ F_{wd} = \frac{1}{8} \rho_w g R^2 B H_s^2 \]  

(3)

Where, \( \rho_w \) is the density of water, \( g \) is the acceleration of gravity, \( R \) is the reflection coefficient assigned according to the shape of the object, and \( H_s \) which
represents the average wave height in the area. The wave induced force increases linearly with velocity and can be described by the following equation:

$$F_{WD}(U) = F_{WD}(0) + UB_{11}$$

(4)

Where, $F_{WD}$ is the force induced by the waves with a forward speed of 0, and $B_{11}$ is the damping constant of the wave force.

Inertial forces.

This force is the sum of the forces generated by the moving object within a fluid and the inertia forces represented by the surrounding fluid, added mass. [3]. The inertial forces of the floating object in motion can be expressed by the following equation:

$$F_i = -(M + A) \ddot{x}$$

(5)

The added mass "A" is a function of the added mass coefficient:

$$A = \rho_w C_A V_R$$

(6)

Where, $C_A$ is the added mass coefficient, $\rho_w$ is the density of water and $V_R$ is the reference volume of the object.

To determine the required pulling force for a maneuver, all previously defined parameters must be calculated following the appropriate assumptions effective for each case, as well as adding a suitable safety margin to ensure a safe maneuver.

Computational fluid mechanics. CFD

The use of CFD tools to solve the equations describing the behavior of a fluid corresponds to an alternative method to estimate the forces generated by the interaction of a fluid flow and a floating body. The set of equations that define the behavior of fluid flow corresponds to the equations of continuity, mass, conservation of energy and momentum, also known as Navier Stokes equations. [4]. These equations can take into account effects such as instability, convection, pressure and viscous effects of a fluid, as well as volumetric forces affecting the phenomenon. The general form of the Navier Stokes equation [5] can be expressed in a simplified form as shown below:

$$\frac{\partial u_i}{\partial t} + u_i \frac{\partial u_i}{\partial x_k} = -\frac{1}{\rho} \frac{\partial p}{\partial x_i} + v \frac{\partial^2 u_i}{\partial x_k \partial x_k} + f_i$$

(7)

The solution of this system of equations is possible for certain cases in which some reductions are valid. For other cases it is possible to use numerical methods and obtain an approximate solution.

Currently, with the help of computational capabilities the application of numerical methods such as the RANS (Reynolds Averaged Navier Stokes) equations coupled to turbulence models related to the mean and fluctuating velocities of a flow, which allow to deliver a very approximate solution. This method corresponds to the one most commonly used in modern CFD packages such as STAR-CCM+, FLUENT, etc.

Case Study

In order to meet the current needs of the Colombian Navy and perform adequate and safe docking maneuvers at the Naval Base located in Malaga Bay in the Western Pacific of Colombia, the analysis of the maximum pulling force required for a tugboat to assist the docking and departure maneuver of ships operating in the area is required.

The maritime characteristics of the area make docking and sailing maneuvers a complex task, especially at times when local weather conditions are not favorable.

The meteorological conditions considered for the analysis take into account the effects of tide-induced currents near the pier of a velocity of 1 knot, and wind gusts from the south-west reaching up to 17 knots [6].

For the analysis, the largest vessels operating in the area will be used, corresponding to the Almirante Padilla Class frigates, whose main characteristics are described in Table 1.
to the maximum drag coefficient generated by the cross sea current; that is, the one produced when the flow is projected in a normal direction on port or starboard side on the hull. The generalized formula used to obtain the drag coefficient considers the submerged longitudinal area:

\[ C_y = \frac{F_y}{\frac{1}{2} \rho U_{ref}^2 L_{ref} T} \]  

(8)

Where, \( U_{ref} \) represents the fluid velocity, \( L_{ref} \) is the length between perpendiculars, \( T \) is the draft of the vessel, and \( F_y \) is the total force exerted by the fluid on the hull. Also, the dimensionless Froude and Reynolds relationships are applied:

\[ R_n = \frac{U_{ref} L_{ref}}{v} \]  

(9)

\[ F_n = \frac{U_{ref}}{\sqrt{\frac{g}{L_{ref}}}} \]  

(10)

Where \( v \) the kinematic viscosity. All CFD calculations presented in this paper make use of the STAR-CCM+ software tool for CFD simulations.

This work follows the general recommendations of the model presented in the CFD review studies of MARIN [7] and Lloyds Register (LR) [8] the OCIMF (Oil Companies International Marine Forum) report for current and wind load predictions for VLCC (VLCC) vessels [9] The study presenting the current and wind drag coefficients interacting with the vessel for different angles of incidence on the vessel.

CFD analysis.

It is important to mention that for this analysis only the water flow is considered, paying special attention to the maximum drag coefficient generated by the cross sea current; that is, the one produced when the flow is projected in a normal direction on port or starboard side on the hull. The generalized formula used to obtain the drag coefficient considers the submerged longitudinal area:

\[ C_y = \frac{F_y}{\frac{1}{2} \rho U_{ref}^2 L_{ref} T} \]  

(8)

Where, \( U_{ref} \) represents the fluid velocity, \( L_{ref} \) is the length between perpendiculars, \( T \) is the draft of the vessel, and \( F_y \) is the total force exerted by the fluid on the hull. Also, the dimensionless Froude and Reynolds relationships are applied:

\[ R_n = \frac{U_{ref} L_{ref}}{v} \]  

(9)

\[ F_n = \frac{U_{ref}}{\sqrt{\frac{g}{L_{ref}}}} \]  

(10)

Where \( v \) the kinematic viscosity. All CFD calculations presented in this paper make use of the STAR-CCM+ software tool for CFD simulations.

Table 2. Recommended band according to ITTC.

<table>
<thead>
<tr>
<th>Scale</th>
<th>( L_{pp} (m) )</th>
<th>( Re )</th>
<th>Tol. (m)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Model</td>
<td>( 1 &lt; L_{pp} &lt; 10 )</td>
<td>( 10^4 \cdot 10^7 )</td>
<td>( \frac{5}{4} )</td>
</tr>
<tr>
<td>Intermediate</td>
<td>( 10 &lt; L_{pp} &lt; 50 )</td>
<td>( 10^7 \cdot 10^8 )</td>
<td>( 5 \times 10^7 )</td>
</tr>
<tr>
<td>Full</td>
<td>( 50 &lt; L_{pp} &lt; 250 )</td>
<td>( 10^9 \cdot 10^{10} )</td>
<td>( \frac{5}{4} )</td>
</tr>
</tbody>
</table>

Taking advantage of computational resources, a scale model of the ship is used according to the recommendations of the ITTC (International Towing Tank Conference). [10]. Table 2 shows the recommended scale band according to the Reynolds number of the full-scale ship. The drag formula for the full-scale vessel according to ITTC can be expressed as:

\[ C_{TS} = (1 + k) C_{FS} + \Delta C_F + C_A + C_R + C_{AS} \]  

(11)

Where \( 1+k \), represents the shape factor obtained from the channel test, \( C_{FS} \) is the friction resistance coefficient, \( C_R \) is the residual resistance coefficient,
\( \Delta_{CF} \) corresponds to the hull roughness factor, \( C_A \) is the allowable correlation and \( C_{AAS} \) is the air resistance coefficient.

Taking into account equations (9) and (11) and the scaling model recommendations according to ITTC on Table 2, the data configuration of the selected CFD scale model to estimate the drag coefficient is presented in Table 3.

<table>
<thead>
<tr>
<th>Table 3. Scaled data of the CFD model.</th>
</tr>
</thead>
<tbody>
<tr>
<td>Scale</td>
</tr>
<tr>
<td>( L_m )</td>
</tr>
<tr>
<td>( B_m )</td>
</tr>
<tr>
<td>( T_m )</td>
</tr>
<tr>
<td>Displacement</td>
</tr>
<tr>
<td>( V_m )</td>
</tr>
<tr>
<td>( Re_m )</td>
</tr>
<tr>
<td>ITTC Reynolds Band</td>
</tr>
<tr>
<td>( Fr_m )</td>
</tr>
</tbody>
</table>

The domain size is designated according to the length between perpendiculars for the numerical simulation according to the LR OCIMF report being: 1.5 L for the fore and aft regions, 2 L starboard and 1 L port, an actual depth of 8 meters and a draft of 3.8 meters, which corresponds to the model scale of 0.532 m and 0.316 m respectively.

As for the recommendations given in the LR OCIMF report, the numerical configuration of the CFD model remains fixed, i.e. without any degree of freedom.

### Turbulence model

This study makes use of the K-Epsilon + SST (Shear Stress Transport) model available in STAR-CCM+ with a Y+30 value and a total of 10 prism layers near the hull and over the bottom of the domain to capture the drag effects produced by shallow depth.

### Mesh considerations

A mesh model was generated following the general recommendations for a traditional drag simulation (forward flow) without taking into account either the propulsion or steering system.

Additional mesh refinements are included to capture flow behavior near the bow and stern. A control volume is also applied to the free surface, although with a smaller number of cells since the simulation works on a subcritical flow; i.e., a Froude number less than 1, and a negligible wave height, as mentioned in the previously cited published work by MARINE and LR. The implemented mesh configuration can be seen in Figs. 3 and 4.

### Boundary conditions.

As mentioned above, the present study considers the model configuration recommendations described in the MARIN and LR documents. The boundary conditions applied to the model are:

- Domain input: speed input.
- Domain output: pressure output.
- Sides of the domain: sliding wall.
- Domain background: no sliding wall.
- Upper limit of the domain: velocity input.
- Vessel: non-slip surface
- Velocity at the scale model inlet: 0.1483 m/s.
  \( \text{(1 knot for the complete ship to scale)} \)
- Free surface: no sliding wall.
Mean draft of the vessel (m), \( d \) is the water depth (m), and \( K \) represents a dimensionless exponent obtained from laboratory data from ship models. For this analytical calculation, the value of \( K = 2 \) is assigned. Table 4 presents the values used for the analytical calculation.

### Table 4. Analytical calculation values according to UFC guidelines to obtain \( \text{Cyc} \).

| \( \text{Cyc} \) | 1.29 |
| \( X \) | 11.24 |
| \( C_m \) | 0.737 |
| \( C_1 \) | 3.2 |
| \( A_m \) | 32.2 |
| \( C_m \) | 0.748 |
| \( B \) (m) | 11.3 |
| \( T \) (m) | 3.8 |
| \( d \) (m) | |
| \( K \) | |

Results.

The \( \text{Cyc} \) calculation is performed with STAR-CCM+ software, and in order to obtain a stable result of the \( \text{Cyc} \) coefficient, the recommendations given by the ITTC are applied, which indicate that the flow should cross the domain up to 5 times its size at least. Considering the current velocity of 0.1483 m/s, the minimum simulation time was estimated at about 100 seconds.

The calculated value is obtained from the average of the last 50 seconds, once the simulation result has reached a stable condition (no large fluctuations).

The UFC guidelines establish the following set of equations for estimating the value of the transverse drag coefficient.

\[
\text{Cyc} = C_0 + (C_1 - C_0) \cdot \left( \frac{T}{D} \right)^K
\]  

(12)

\[
C_0 = 0.22 \cdot \sqrt{X}
\]  

(13)

\[
X = \frac{L_{wL}^2}{B \cdot V}
\]  

(14)

Where, \( L_{wL} \) is the length of the vessel at the waterline (m), \( A_m \) is the submerged cross-sectional area of the vessel at the midsection (m²), \( B \) is the beam at the waterline (m), \( V \) is the submerged volume of the vessel, (m³), \( C_1 \) is the current force drag coefficient for shallow water where \( T/d = 1 \); for currents of 4.9 ft/s (2.9 knots or 1.5 m/s) or less; a value of \( C_1 = 3.2 \) is recommended, \( C_0 \) is the drag coefficient for deep water, \( T \) is the mean draft of the vessel (m), \( d \) is the water depth (m), and \( K \) represents a dimensionless exponent obtained from laboratory data from ship models. For this analytical calculation, the value of \( K = 2 \) is assigned. Table 4 presents the values used for the analytical calculation.

Proceeding to the CFD numerical calculation, the first \( \text{Cyc} \) coefficient obtained was 2.08, which is considerably higher than the value of 1.29 obtained using the guidelines of the UFC manual.

In order to obtain reliable results, a mesh independence analysis is performed. This analysis consists of increasing the number of cells, making a refinement of the mesh in order to reduce the difference of the immediately comparable results obtained from the coefficient.
increasing the final value of Cyc, as predicted by the CFD results.

The Fig. 8 provides the velocity field distribution around the vessel showing zones with low velocity magnitudes, which create a high pressure zone thus increasing the drag coefficient acting on the vessel hull.

Conclusions

The CFD study has been carried out to estimate the drag coefficient Cyc necessary for the calculation of the pulling force required to estimate the required power of the tugboat with the capacity to perform the maneuvering operations to the ships at the naval base of Bahía Málaga, Colombia.

The simulation setup has been performed based on the recommended procedure published in the Lloyds Register OCIMF and the CFU manual for current drag coefficient estimation.

The analytical formulation provided by the UFC manual to calculate the current drag coefficient Cyc, using the predefined constants applicable to general ships and barges, has shown a lower value in magnitude for Cyc compared to that obtained by CFD analysis. This leads to the conclusion that the current drag coefficient calculated using the UFC guidelines may underestimate the current forces, with CFD analysis being a more reliable method for estimating this coefficient.

From the results it can also be concluded that the Cyc coefficient can vary significantly depending

---

Fig. 6. Variation of the Cyc coefficient by changing the dimensionless coefficient K and C₀ in equation 12 v

Fig. 7. Stern view showing the presence of vortices.

The Fig. 6 shows the variation of the constant K with respect to the change of the transverse drag coefficient Cyc for the UFC formulation. With a value of Cyc of 1.55, as well as a deepwater drag coefficient C₀ of 1.0212 obtained using CFD, the value of K that equals Equation 12 would have a final value 1.9.

The Fig. 7 shows the velocity field obtained from the CFD simulation. The high-pressure zone with vortices can be observed, which increases the total drag force generated by the stream flow, thus
on the hull shape, and in order to use the formulation presented in the UFC manual for the estimation of current induced forces, a safety margin must be included when calculating the required pulling force.

References


